

Applications of MC methods

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Optimization problem:

We have a set $X \subset \mathbb{R}^m$ and a function $F : X \rightarrow \mathbb{R}$.

Task:

Find the optimum point:

$$x_{opt} \in X : \forall_{x \in X} F(x) \geq F(x_{opt})$$

⇒ This is completely different than normal function minimalization as we choose x_{opt} from a set X . This makes a big difference for numerical computations.

⇒ The MC algorithms for solving this problem:

- Hit and miss method - the simplest and the slowest.
- Sequence methods - MC interpretation of method of further approximations.
- Genetic methods, stat. optimization.

Optimization hit and miss

⇒ The algorithm acts as follows:

- We generate N points $x_1, \dots, x_N \in X$ from a constant p.d.f. on X .
- We calculate the F function value in the points x_1, \dots, x_N :

$$F_1 = F(x_1), \quad F_2 = F(x_2), \quad \dots, \quad F_N$$

- We calculate $F^* = \min\{F_1, F_2, \dots, F_N\}$.
- The solution is $x_j : F(x_j) = F^*$

⇒ Precision:

If $F^* = \min_{1 \leq j \leq N} \{F(x_j)\}$ where $x_j = 1, 2, \dots, N$ are random points from uniform p.d.f. on X . Then with the probability $1 - (1 - \gamma)^N$ the volume of points x for which $F(x) < F^*$ is smaller than ϵ .

⇒ We can say that with probability $1 - (1 - \gamma)^N$ the points x_{opt} was localized with the probability γ .

⇒ the smaller the volume the better the accuracy.

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Optimization hit and miss

The smallest N that obeys: $1 - (1 - \gamma)^N \geq 1 - \epsilon$:

γ	$1 - \epsilon$					
	0.5	0.9	0.95	0.99	0.999	0.9999
0.5	1	4	5	7	10	14
0.1	7	22	29	44	66	88
0.05	14	45	59	90	135	180
0.01	69	230	299	459	688	917
0.001	693	2302	2995	4603	6905	9206
0.0001	6932	23025	29956	46050	69075	92099

⇒ Example: $[0, 1]^m$ and $F : X \rightarrow \mathbb{R}$.

How many points we need to generate to have 0.9 probability to be have half of the range of each direction in each precision:

- For $m = 1$: $\gamma = 1/2 \mapsto N = 4$.
- For $m = 2$: $\gamma = 1/4 \mapsto N = 9$.
- For $m = 14$: $\gamma = 2^{-14} \mapsto N > 23\,000$.

⇒ Inefficient for multi-dimensions.

Optimization sequence

⇒ The algorithm:

- We choose the starting point $x_1 \in X$ from some p.d.f. on X set.
- After generating x_1, x_2, \dots, x_n check if some conditions are meet.
 - If YES then we stop and we put x_n as solution.
 - If NO then we generate x_{n+1} form a p.d.f. that depends on already generated points.

⇒ The basic sequence algorithm:

- Choose x_1 .
- After we have x_1, x_2, \dots, x_n then we generate a temporary point ξ_n :

$$x_{n+1} = \begin{cases} x_n, & \text{if } F(x_n + \xi_n) \geq F(x_n) - \epsilon \\ x_n + \xi_n, & \text{if } F(x_n + \xi_n) < F(x_n) - \epsilon \end{cases}$$

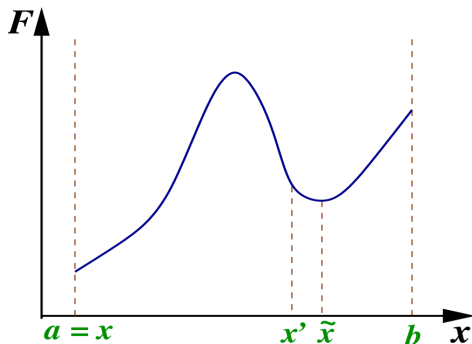
Optimization sequence

⇒ From the above algorithm we will get a sequence:

$$F(x_1) \geq F(x_2) \geq F(x_3) \geq \dots \geq F(x_n) \geq F(x_{n+1}) \dots$$

⇒ If the function is bounded from the bottom the the above sequence is converging.

⇒ How can we be sure it will converge to x_{opt} ?



⇒ If we choose the correct the P_n every sequence starting from x' will converge to \tilde{x} , where F has a local minimum.

Optimization sequence

⇒ There are two types of algorithms:

- If the algorithm can find the global minimum then we call it: global algorithm.
- If the algorithm can find only local minimum then we call it: local algorithm.

⇒ If in the sequence $\{x_n\}$ we find a point x' such that:

$$F(x_{opt}) < F(x') < F(x_{opt}) + \epsilon$$

then the above algorithm will converge only to x' .

⇒ Of course we can change the ϵ such that we escape the x' .

Q & A

Backup