Extracting angular observables with Method of Moments

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- 1. Motivation.
- 2. Method of Moments.
- 3. Systematic uncertainties.
- 4. MC toy studies.
- 5. Conclusions.

Likelihood(LL) fits even though widely used suffer from couple of draw backs:

- 1. In case of small number events LL fits suffer from convergence problems. This behaviour is well known and was observed several times in toys when we done  $B \rightarrow K^* \mu \mu$ .
- **2.** LL can exhibit a bias when underlying physics model is not well known, incomplete or mismodeled.
- **3.** The LL have problems converging when parameters of the p.d.f. are close to their physical boundaries, so-called "boundary problem"
- 4. Accessing uncertainty in LL in some cases requires application of computationally expensive Feldman-Cousins method.



MoM solves the above problems:

#### Advantages of MoM

- Probability distribution function rapidity converges towards the Gaussian distribution.
- MoM gives an unbias result even with small data sample.
- Insensitive to large class of remodelling of physics models.
- Is completely insensitive to boundary problems.



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#### Advantages of MoM

- Each observable can be determined separately from other.
- Uncertainly follows perfectly  $1/\sqrt{N}$  scaling.



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#### **Advantages of MoM**

 Estimated uncertainty in MoM is larger then the ones from LL.



## Introduction to MoM

Let us a define a probability density function p.d.f. of a decay:

$$P(\vec{\nu}, \vec{\vartheta}) \equiv \sum_{i} S_{i}(\vec{\nu}) \times f_{i}(\vec{\vartheta})$$
(1)

Let's assume further that there exist a dual basis:  $\{f_i(\vec{\vartheta})\}$ ,  $\{\tilde{f}_i(\vec{\vartheta})\}$  that the orthogonality relation is valid:

$$\int_{\Omega} \mathrm{d}\vec{\vartheta} \, \tilde{f}_i(\vec{\vartheta}) f_j(\vec{\vartheta}) = \delta_{ij} \tag{2}$$

Since we want to use MoM to extract angular observables it's normal to work with Legendre polynomials. In this case we can find self-dual basis:

$$\forall_i \tilde{f}_i = f_i , \qquad (3)$$

just by applying the ansatz:  $\tilde{f}_i = \sum_i a_{ij} f_j$ .



### **Determination of angular observables**

Thanks to the orthonormality relation Eq. 2 one can calculate the  $S_i(\vec{\nu})$  just by doing the integration:

$$S_i(\vec{\nu}) = \int_{\Omega} d\vec{\vartheta} P(\vec{\nu}, \vec{\vartheta}) \tilde{f}_i(\vec{\vartheta})$$
(4)

We also need to integrate out the  $\vec{\nu}$  dependence:

$$\langle S_i \rangle = \int_{\Theta} d\vec{\nu} \int_{\Omega} d\vec{\vartheta} P(\vec{\nu}, \vec{\vartheta}) \tilde{f}_i(\vec{\vartheta})$$
(5)

MoM is basically performing integration in Eq. 5 using MC method:

$$E[S_i] \to \widehat{E[S_i]} = \frac{1}{N} \sum_{k=1}^N \widetilde{f}(x_k)$$



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MoM provides also a very fast and easy way of estimating the statistical uncertainty:

$$\sigma(S_i) = \sqrt{\frac{1}{N-1} \sum_{k=1}^{N} (\tilde{f}_i(x_k) - \hat{S}_i)^2}$$
(6)

and the covariance:

$$\operatorname{Cov}[S_i, S_j] = \frac{1}{N-1} \sum_{k=1}^{N} [\widehat{S}_i - \widetilde{f}_i(x_k)] [\widehat{S}_j - \widetilde{f}_j(x_k)]$$
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# Partial Waves mismodeling

- Let us consider a decay of  $B \rightarrow P_1 P_2 \mu^- \mu^+$ .
- In terms of angular p.d.f. is expressed in terms of partial-wave expansion.
- ► For  $B \rightarrow K\pi\mu^{-}\mu^{+}$  system, S,P,D waves have been studied.



 The hadron system can have arbitrary large angular momentum.





# Partial Waves mismodeling

One can write the p.d.f. separating the hadronic system:

$$P(\cos\vartheta_1,\cos\vartheta_2,\vartheta_3) = (8)$$
$$\sum_i S_i(\vec{\nu},\cos\vartheta_2)f_i(\cos\vartheta_1,\vartheta_3)$$



S<sub>i</sub>(ν, cos ϑ<sub>2</sub>) can be further expend in terms of Legendre polynomials p<sub>l</sub><sup>|m|</sup>(cos ϑ<sub>2</sub>):

$$S_i(\vec{\nu}, \cos\vartheta_2) = \sum_{l=0}^{\inf} S_{k,l}(\vec{\nu}) p_l^{|m|}(\cos\vartheta_2)$$
(9)

Experimentally the S<sub>k,l</sub> are easily accessible, but there is a theoretical difficulty as one would need to sum over infinite number of partial waves.

## **Detector effects**

Since our detectors are not a perfect devices the angular distribution observed by them are not the distributions that the physics model creates.



- To take into account the acceptance effects one needs to simulate the a large sample of MC events.
   Try to figure out the efficiency function.
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- Number of possibilities.
- Then you can just weight events:



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  - Number of possibilities.
  - Then you can just weight events:

$$\widehat{E[S_i]} = \frac{1}{\sum_{k=1}^{N} w_k} \sum_{k=1}^{N} w_k \tilde{f}(x_k), \ w_k = \frac{1}{\epsilon(x_k)} \qquad ()$$

# **Unfolding matrix**

In general one can write the distribution of events after the detector effects:

$$P^{\mathrm{Det}}(x_d) = N \int \int dx_t \ dx_d \ P^{\mathrm{Phys}}(x_t) E(x_d | x_t), \qquad (10)$$

where  $N^{-1} = \int \int dx_t \, dx_d \, P^{\text{Phys}}(x_t) E(x_d|x_t)$  and  $(x_d|x_t)$  denotes the efficiency  $\epsilon(x_t)$  and resolution of the detector  $R(x_d|x_t)$ :

$$E(x_d|x_t) = \epsilon(x_t)R(x_d|x_t)$$
(11)

One can define the raw moments:

$$Q_i^{(m)} = \int \int dx_t \ dx_d \ \tilde{f}_i(x_d) P^{(m)}(x_t) E(x_d | x_t)$$
(12)

The *m* index corresponds to simulation sample that has  $S_0$  and  $S_m$  observables set to  $\frac{1}{2}$  and rest to zero.

# **Unfolding matrix**

Once again we can use MC estimator:

$$Q_i^{(m)} \to \widehat{Q}_i^{(m)} = \frac{1}{N_t} \sum_{i}^{N_d} \widetilde{f}_i(x_d^{i,m})$$
(10)

Linearity of the integral ensures that there has to exists a linear transformation:

$$\vec{Q} = M\vec{S},\tag{11}$$

where M is so-called unfolding matrix, given by the formula:

$$M_{ij} = \begin{cases} 2Q_i^{(0)} & j = 0, \\ 2\left(Q_i^{(j)} - Q_i^{(0)}\right) & j \neq 0, \end{cases}$$
(12)

Once we measured the moments Q in data we can invert Eq. 11 and get the  $\vec{S}$  :

$$\widehat{\vec{S}} = M^{-1}\widehat{\vec{Q}},$$



- All the statistics properties of MoM have been tested in numbers of TOY MC.
- ► As long as you have ~ 30 events your pulls are perfectly gaussian.
- Uncertainty scales with  $\frac{\alpha}{\sqrt{n}}$ ,  $\alpha = \mathcal{O}(1)$ .
- Never observed any boundary problems.



## **Correlation of MoM with Likelihood**

- MoM is highly correlated with LL.
- Despite the correlation there can be difference of the order of statistical error.





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Extracting angular observables with Method of Moments

- 1. MoM posses several big advantages with one drawback which is larger statistical uncertainty.
- **2.** Allows us to go smaller  $q^2$  bins (get ready for 1 GeV<sup>2</sup> soon!).
- 3. Alternative method of extracting the detector effects.
- 4. Can be applied to various rare decays.

