Method of moments for $B \to K^* \mu \mu$



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- 1 Introduction
- 2 Method of Moments Theory
- Moments of Ss
- **4** Toy MC study
- **5** 2 am discovery



Plan

Why method of moments:

- Complementary approach in performing the fit.
- Allows to extract info measuring quantities in event basis depending on the angular distribution.
- ③ Used in B $\rightarrow \rho\ell\nu$ (SLAC-386 UC-414), J/ $\psi \rightarrow$ KK γ (PRD 71, 032005 (2005)), etc.



Method of moments

Let's assume we have our pdf with k unknown parameters : $PDF(x_i, \alpha)$, $dim(\alpha) = k$. One can calculate k moments, which are the functions of α_i :

$$\mu_i = f(\alpha_1, ..., \alpha_k) = E[W_i] \tag{1}$$

If we have n events in our q^2 bin, we can estimate:

$$\widehat{\mu}_i = \frac{1}{n} \sum_{j=0}^{J=n-1} w_j \tag{2}$$

, where $w_i = g(x_i)$



Lets see how this works in practice:

$$f(x) = \frac{x^{a-1}e^{-x/b}}{b^{a}\Gamma(a)}$$
 (3)

we measure the moments:

$$m_1 = \frac{X_1 + X_2 + \dots + X_n}{n},$$

 $m_2 = \frac{X_1^2 + X_2^2 + \dots + X_n^2}{n}.$

and calculate them analytically:

$$m_1 = ab$$
, $m_2 = b^2 a(a+1)$

So one just needs to solve this and get the answer:

$$a = \frac{m_1^2}{m_2 - m_1^2}, \ b = \frac{m_2 - m_1^2}{m_1}$$



Our PDF

The angular terms:

$$\frac{d^4\Gamma}{dq^2d\cos\theta_k d\cos\theta_l d\phi} = \frac{9}{32\pi} (\frac{3}{4}(1-F_l)\sin^2\theta_k + F_l\cos^2\theta_k + (\frac{1}{4}(1-F_l)\sin^2\theta_k - F_l\cos^2)\cos 2\theta_l + J_3\sin^2\theta_k \sin^2\theta_l\cos 2\phi + J_4\sin 2\theta_k \sin \theta_l\cos \phi + J_5\sin 2\theta_k \sin \theta_l\cos \phi + (J_{6s}\sin^2\theta_k + J_{6c}\cos^2\theta_k)\cos \theta_l + J_7\sin 2\theta_k \sin \theta_l\sin \phi + J_8\sin 2\theta_k \sin 2\theta_l\sin \phi + J_9\sin^2\theta_k\sin 2\phi)$$
 (4)

Since we are fitting a PDF we need to ensure it is normalized:

$$\int_{-\pi}^{\pi} d\phi \int_{-1}^{1} d\cos\theta_{l} \int_{-1}^{1} d\cos\theta_{k} \frac{d^{4}\Gamma}{dq^{2}d\cos\theta_{k}d\cos\theta_{l}d\phi} = 1$$
 (5)



From equation 2 we have the following:

$$\frac{1}{4}(3J_{1c} + 6J_{1s} - J_{2c} - 2J_{2s}) = 1 \tag{6}$$

For now we will consider the following PDF:

$$\frac{d^{3}\Gamma}{\Gamma d\cos\theta_{k} d\cos\theta_{l} d\phi} (\cos\theta_{k}, \cos\theta_{l}, \phi) \tag{7}$$

Becouse our PDF is not normalized and we are measuring $\Gamma + \overline{\Gamma}$ we are effectively fitting the S_i (aka $J_i \rightarrow S_i$)



Let's calculate the moments for Ss:

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin^{2}\theta_{k}sin^{2}\theta_{l}cos2\phi = \frac{8S_{3}}{25}$$
 (8)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin2\theta_{k}sin2\theta_{k}cos\phi = \frac{8S_{4}}{25}$$
 (9)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin2\theta_{k}sin\theta_{l}cos\phi = \frac{2S_{5}}{5}$$
 (10)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin2\theta_{k}sin\theta_{l}sin\phi = \frac{2S_{7}}{5}$$
 (11)

$$\frac{d^{3}\Gamma}{\Gamma d\cos\theta_{k} d\cos\theta_{l} d\phi} \sin 2\theta_{k} \sin 2\theta_{l} \sin\phi = \frac{8S_{8}}{25}$$
 (12)



- The simplest solution one could imagine.
- We are abusing the fact that the basis is orthogonal.
- Each of the I doesn't know about other.
- Only S_{1s} , S_{2s} , S_{1c} , S_{2c} and S_{6s} , S_{6c} are not orthogonal, but to get the answer you just need to solve a linear equation system so it's not a tragedy.

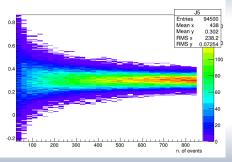
$$\frac{d^{3}\Gamma}{\Gamma d\cos\theta_{k} d\cos\theta_{l} d\phi} \sin^{2}\theta_{k} \cos\theta_{l} = 0.1(S_{6}c + 4S_{6}s) \tag{13}$$

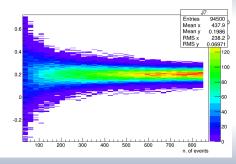
$$\frac{d^3\Gamma}{\Gamma d\cos\theta_k d\cos\theta_l d\phi} \cos\theta_l = 0.25(S_6 c + 2S_{6s}) \tag{14}$$

solution:
$$S_{6c} = 2(4M_{S_{6c}} - 5M_{S_{6s}})$$
, $S_{6s} = -2M_{S_{6c}} + 5M_{S_{6s}}$



Lets see if this method actually works. Let's take some random parameters for the PDF and make a toy.

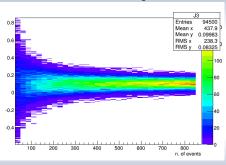


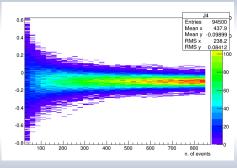


• let's take 300 signal events as a working case.



Lets see if this method actually works. Let's take some random parameters for the PDF and make a toy.

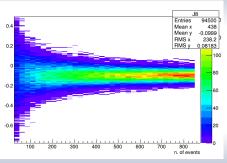


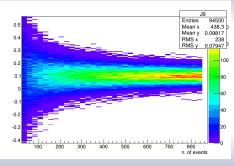


• let's take 300 signal events as a working case... we might still change the binning



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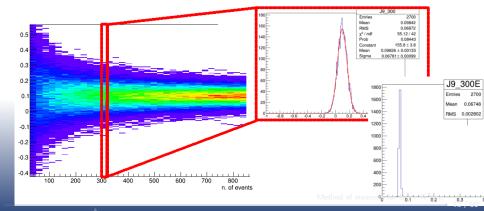


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Error Estimation

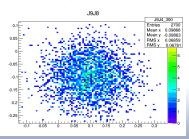
- ullet Since moment is the mean of a given distribution the error can be estimated as mean/RMS
- use TOY MC to check this assumption

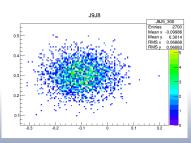




Correlation check

- In theory S_i shouldn't be correlated to S_i in the moment calculation.
- Lets put this to a test.

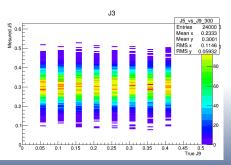


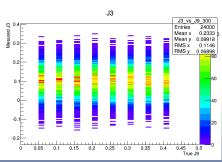




Correlation check 2

- Let's now FIX J_x and simulate different J_y
- Again theory would suggest that one J shouldn't know about the other, so J_x shouldn't change with scanning J_y parameter







What will happen to our problem with an S-wave?

Reminder:

$$\frac{d^{4}\Gamma}{dq^{2}d\cos\theta_{k}d\cos\theta_{l}d\phi} = \frac{9}{32\pi} (J_{1s}sin^{2}\theta_{k} + J_{1c}cos^{2}\theta_{k} + (J_{2s}sin^{2}\theta_{k} + J_{2c}cos^{2})\cos2\theta_{l} + J_{3}sin^{2}\theta_{k}sin^{2}\theta_{l}\cos2\phi + J_{4}sin2\theta_{k}sin\theta_{l}\cos\phi + J_{5}sin2\theta_{k}sin\theta_{l}\cos\phi + (J_{6s}sin^{2}\theta_{k} + J_{6c}\cos^{2}\theta_{k})\cos\theta_{l} + J_{7}sin2\theta_{k}sin\theta_{l}\sin\phi + J_{8}sin2\theta_{k}sin2\theta_{l}sinphi + J_{9}sin^{2}\theta_{k}sin^{2}\theta_{l}sin2\phi)$$
(15)

Let's add a very discussing things that keeps us awake at night:

$$W_{s} = \frac{2}{3}F_{s}\sin^{2}\theta_{I} + \frac{4}{3}A_{s}\sin^{2}\theta_{I}\cos\theta_{k} + I_{4}\sin\theta_{k}\sin2\theta_{I}\cos\phi$$
$$+ I_{5}\sin\theta_{k}\sin\theta_{I}\cos\phi + I_{7}\sin\theta_{k}\sin\theta_{I} + \sin\phi + I_{8}\sin\theta_{k}\sin2\theta_{I}\sin\phi) \quad (16)$$



What will happen to our problem with an S-wave?

So now our PDF is sum of eq. 15 and 16. Of coz we need to require normalization:

$$\frac{1}{12}(32I_{1a} + 9J_{1c} + 18J_{1s} - 3J_{2c} - 6J_{2s}) = 1$$
 (17)

No surprises here. If we have a S-wave it has to enter in Γ . To build up the preasure, what will happen to our Ss?



NOTHING!!!!!!!!

We are completely insensitive to S-wave:

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin^{2}\theta_{k}sin^{2}\theta_{l}cos2\phi = \frac{8S_{3}}{25}$$
 (18)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin2\theta_{k}sin2\theta_{k}cos\phi = \frac{8S_{4}}{25}$$
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 (21)

$$\frac{d^{3}\Gamma}{\Gamma d\cos\theta_{k} d\cos\theta_{l} d\phi} \sin 2\theta_{k} \sin 2\theta_{l} \sin\phi = \frac{8S_{8}}{25}$$
 (22)



Thins get better :)

We can even measure directly the S-wave:

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin^{2}\theta_{l}cos\theta_{k} = \frac{32I_{1b}}{45}$$
 (23)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin\theta_{k}sin2\theta_{l}cos\phi = \frac{16I_{4}}{45}$$
 (24)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin\theta_{k}sin\theta_{l}cos\phi = \frac{4I_{5}}{9}$$
 (25)

$$\frac{d^{3}\Gamma}{\Gamma dcos\theta_{k}dcos\theta_{l}d\phi}sin\theta_{k}sin2\theta_{l}sin\phi = \frac{4I_{7}}{9}$$
 (26)

$$\frac{d^{3}\Gamma}{\Gamma d\cos\theta_{k} d\cos\theta_{l} d\phi} \sin\theta_{k} \sin2\theta_{l} \sin\phi = \frac{16S_{8}}{45}$$
 (27)



Conclusions on S-wave

- S-wave components are transparent to method of moments.
- If they are orthogonal to others all they toy studies holds for them as well(will reapat for robustness but can bet my house that there is nothing going on there).

•



Conclusions

- Implemented moments method for the K*mm and start testing with toy MC
- The method converge fast and works for the "simple case", i.e. signal only.
- Method completely insensitive to S-wave component, thanks to orthogonality.
- Complementary one can measure in-depended S-wave component.

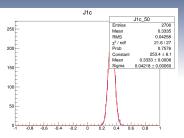
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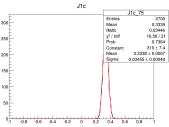
- add realism: backgrounds
- Do the unfolding
- Study binning

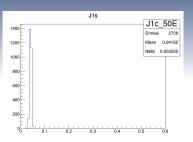


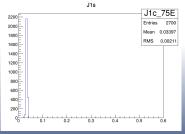
BACKUPS



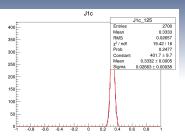


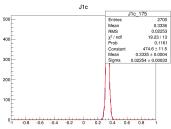


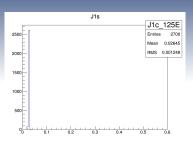


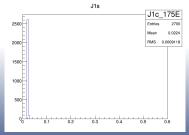




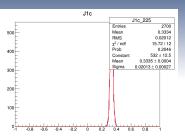


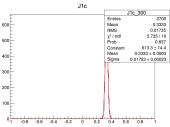


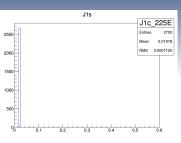


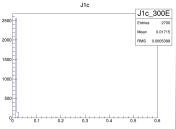




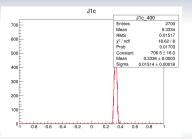


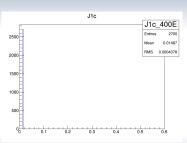




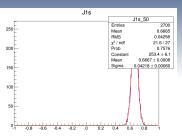


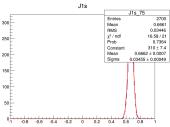


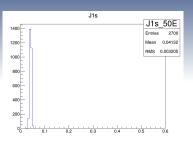


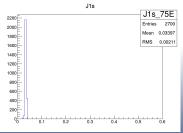




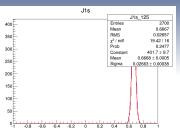


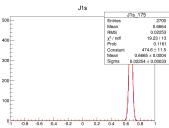


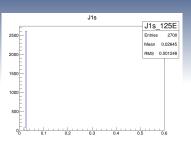


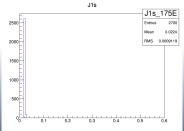




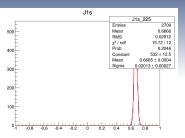


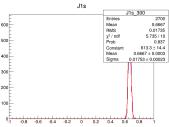


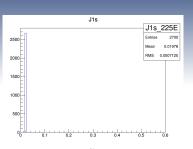


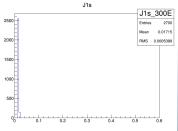




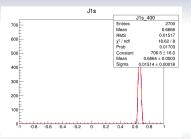


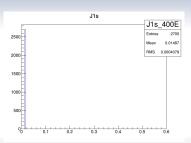




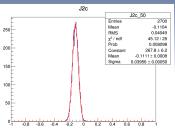


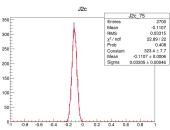


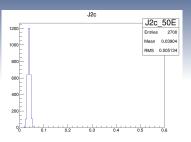


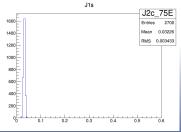




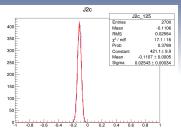


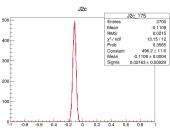


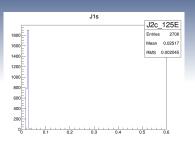


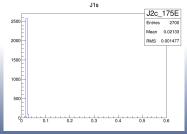




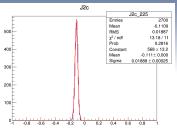


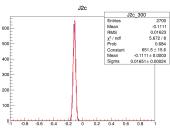


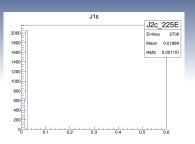


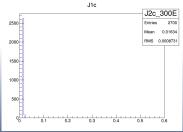




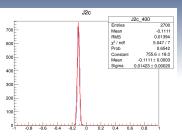


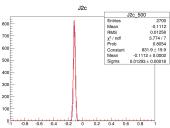


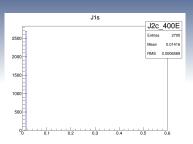


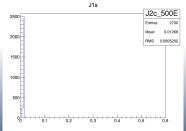




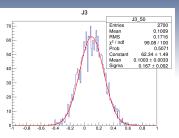


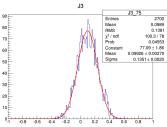


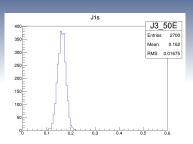


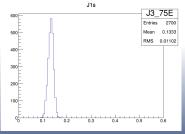




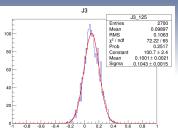


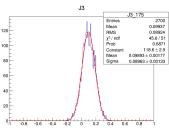


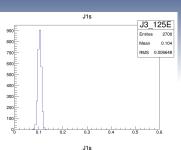


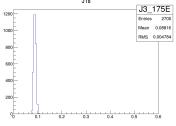




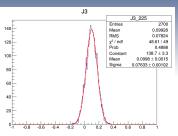


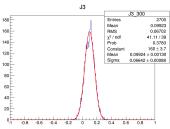


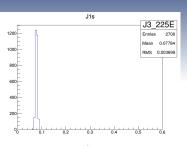


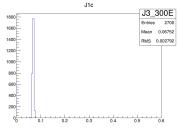




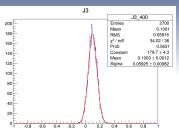


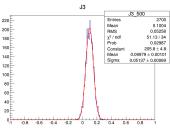


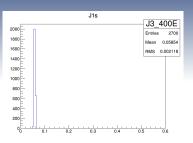


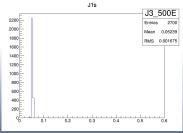




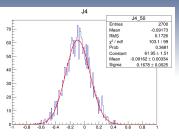


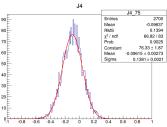


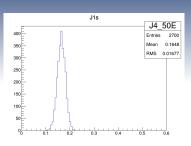


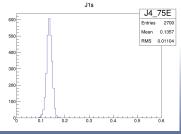




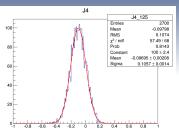


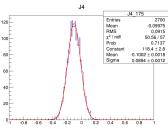


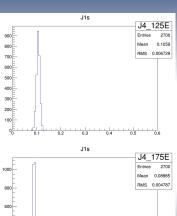


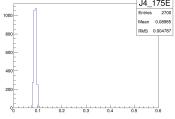




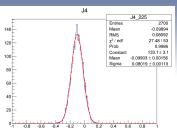


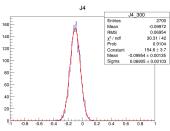


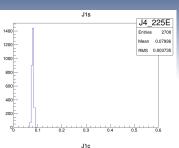


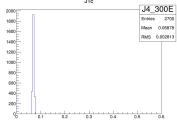




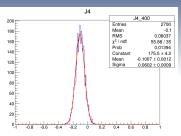


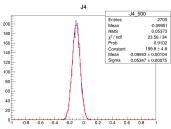


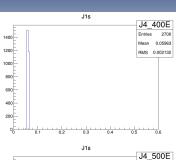


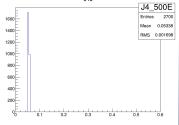




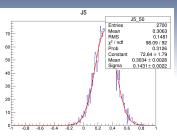


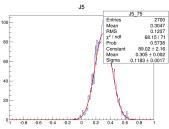


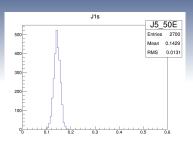


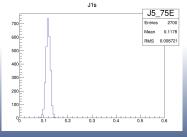




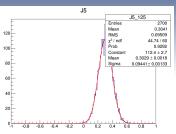


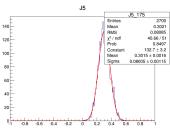


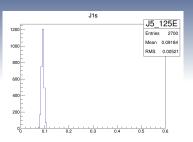


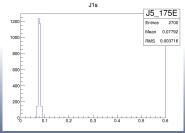




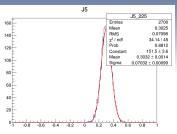


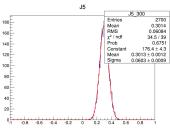


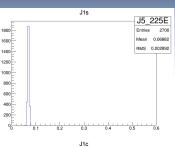


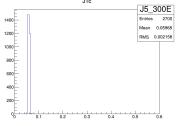




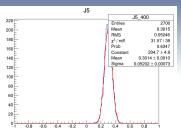


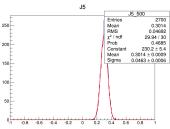


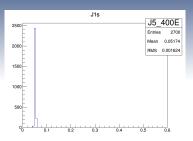


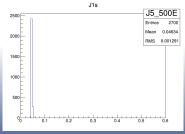




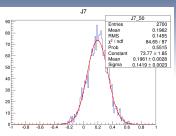


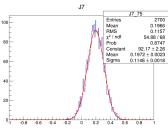


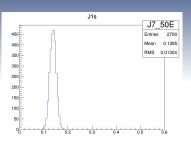


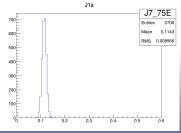




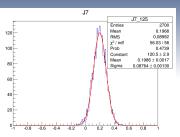


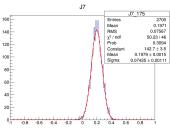


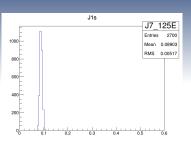


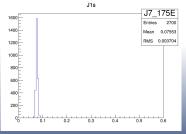




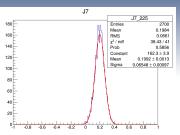


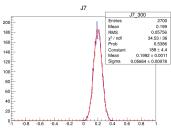


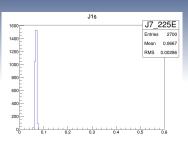


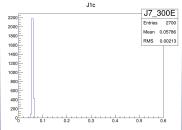




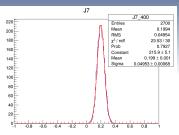


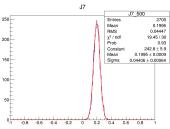


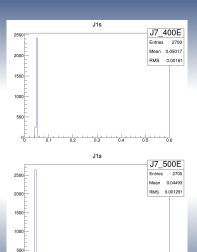




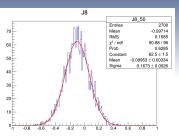


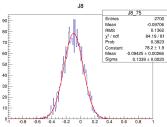


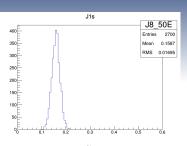


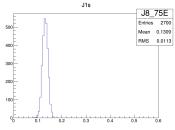




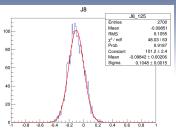


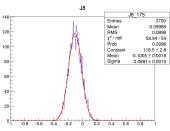


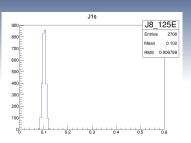


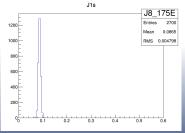




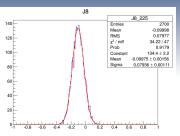


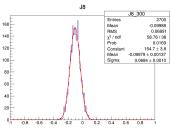


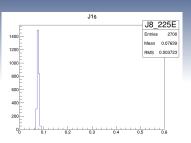


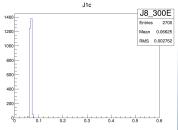




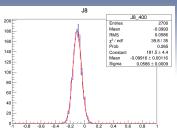


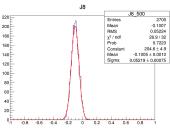


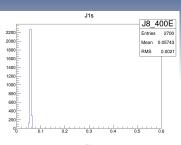


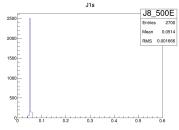




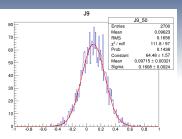


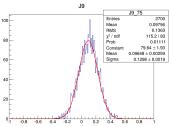


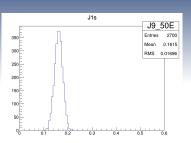


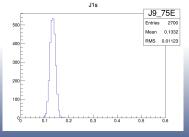




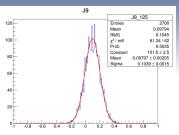


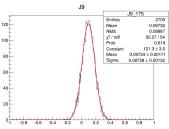


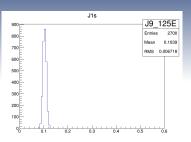


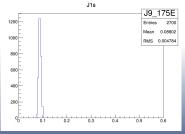




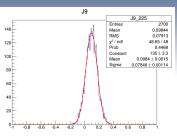


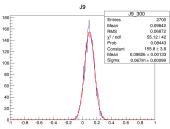


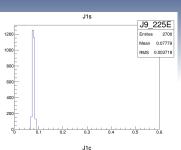


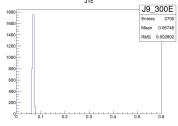




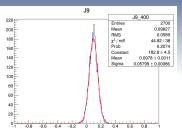


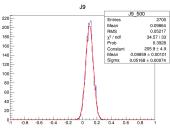


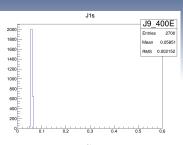


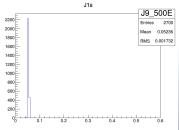




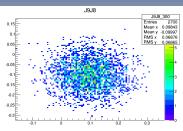


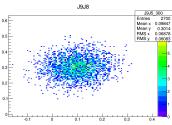


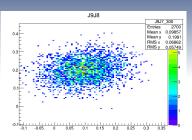


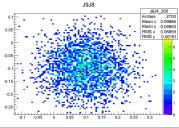




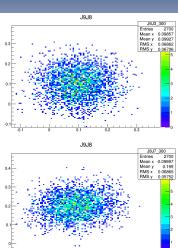












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