

# Unfolding for counting experiments

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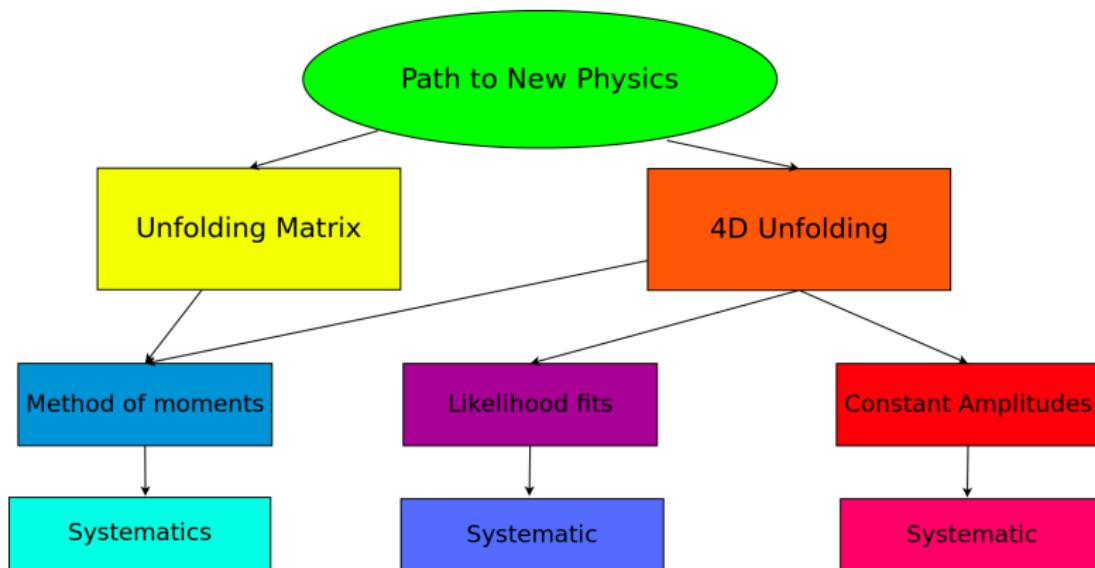
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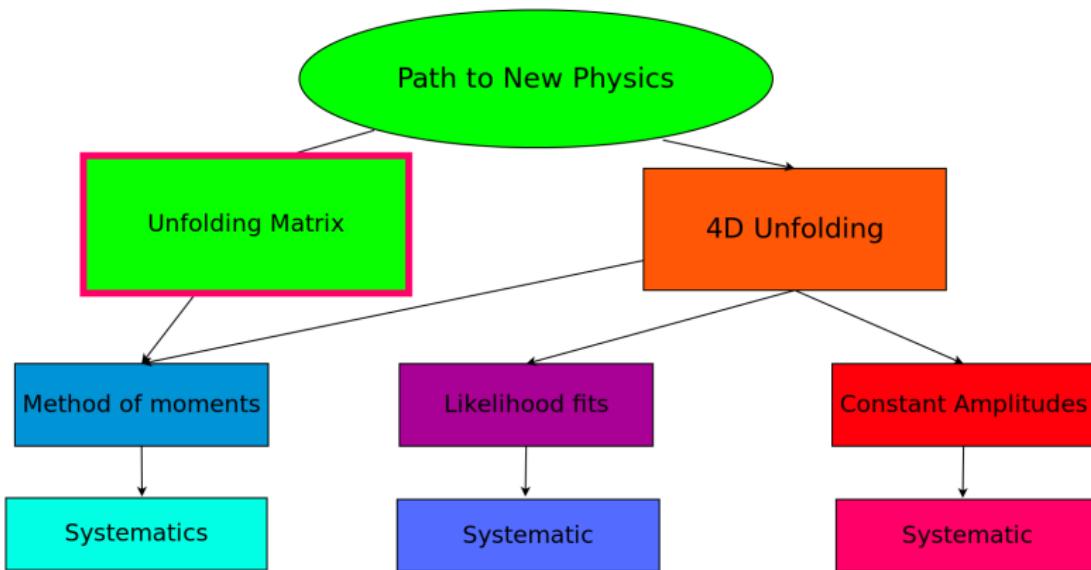
# Quo vadis $B^0 \rightarrow K^*\mu\mu$ ?



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# Quo vadis $B^0 \rightarrow K^* \mu\mu$ ?



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# 4D unfolding

- Method of moments can use 2 different unfolding techniques.
- One of them is Christophs 4D unfolding
- Easy peasy:

$$\hat{x} = \sum_i^n = \frac{f(\theta_{li}, \theta_{ki}, \phi_i)}{n} \rightarrow \frac{f(\theta_{li}, \theta_{ki}, \phi_i) \times w_i}{\sum_j^n w_j} \quad (1)$$

Very easy and has proved to work. See presentation [LINK](#)



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# Matrix unfolding

- Our PDF is a vector in 8 dim space, where the dimensions are:  
 $f_x^1$
- Our acceptance is a function:

$$\epsilon(\cos \theta_k, \cos \theta_l, \phi) \quad (2)$$

- We assume it's a smooth function( $C^\infty$ ).
- Normal moments:

$$M_x = \int PDF \times f_x \rightarrow \overline{M_x} = \int PDF \times f_x \times \epsilon(\cos \theta_k, \cos \theta_l, \phi) \quad (3)$$

- Let's play Christophs trick:

$$\epsilon(\cos \theta_k, \cos \theta_l, \phi) = \sum A_{\alpha, \beta, \gamma} \cos^\alpha \theta_k \cos^\beta \theta_l \phi^\gamma \quad (4)$$

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<sup>1</sup>See 1st presentation on Method of moments.

# Matrix unfolding

- Our Moments will become:

$$\int PDF \times f_x \times \epsilon(\cos \theta_k, \cos \theta_l, \phi) = \sum A_{\alpha, \beta, \gamma} \int PDF \times f_x \times \cos^\alpha \theta_k \cos^\beta \theta_l \phi^\gamma \quad (5)$$

- We just need to show that:

$$\int PDF \times f_x \times \cos^\alpha \theta_k \cos^\beta \theta_l \phi^\gamma = \sum_y B_y \int PDF \times f_y = \sum_y B_y M_y \quad (6)$$

- This is a bit nasty but doable, using Mathematica. You just need to check 8 base functions.
- As expected it's is linear terms.
- I also checked this using analytical calculations.



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# Constructing Matrix unfolding

- Ok, so we know that the matrix exists.
- However we don't know explicate

$$\epsilon(\cos \theta_k, \cos \theta_I, \phi) \quad (7)$$

- We don't, we just need to calculate matrix elements
- Let's use PHSP MC.
- Moments for PHSP MC are:  
 $v_{gen}^T = (2/3, 0, 0, 0, 0, 0, 0, 0)$
- After reconstruction we get:  $v_{rec}^T = (0.7069, 0.0077, -0.00236466, 0.0005, 0.0007, 0.0011, 0.0011, -0.0012)$

# Constructing Matrix unfolding

- We got first column of the unfolding matrix.

$$\begin{pmatrix} 1.06 & \cdots & a_{1,8} \\ 0.01157 & \cdots & a_{2,8} \\ -0.003547 & \ddots & \vdots \\ 0.0007841 & \ddots & \vdots \\ 0.0011126 & \ddots & \vdots \\ 0.001766 & \ddots & \vdots \\ 0.001664 & \ddots & \vdots \\ -0.001937 & \cdots & a_{8,8} \end{pmatrix}$$

- How about the others?
- We can reweight accordingly to  $f_x$ .



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# Constructing Matrix unfolding

- To get  $S_3$  each event  $i^{th}$  has weight  $f_{S_3}(\cos \theta_{k_i}, \cos \theta_{l_i}, \phi_i)$
- One can calculate on MC the reweighed moments in PHPS:

$$\int PDF * f_{S_3} = \frac{32}{225} \quad (8)$$

- Our base vector now is:  $v_{gen}^T = (0, \frac{32}{225}, 0, 0, 0, 0, 0, 0, 0)$
- So lets see what do we get as reconstructed vector(after multiplying by  $\frac{225}{32}$ ).  $v_{rec}^T = (0.042, 1.105, -0.005, 0.003, -0.0023, -0.005, -0.005, -0.006)$

# Constructing Matrix unfolding

- Now the matrix looks like:

$$\begin{pmatrix} 1.06 & 0.042 & \cdots & a_{1,8} \\ 0.01157 & 1.105 & \cdots & a_{2,8} \\ -0.003547 & -0.005 & \ddots & \vdots \\ 0.0007841 & -0.005 & \ddots & \vdots \\ 0.001126 & 0.003 & \ddots & \vdots \\ 0.001766 & -0.0023 & \ddots & \vdots \\ 0.001664 & -0.005 & \ddots & \vdots \\ -0.001937 & -0.006 & \cdots & a_{8,8} \end{pmatrix}$$

- The others go in the same way.
- Repeating this exercise from 1<sup>st</sup> year algebra we can get the full matrix

# Constructing Matrix unfolding

- The full transformation matrix from generator space to reconstructed space:

$$A_{gen \rightarrow reco} =$$

$$\begin{pmatrix} 1.06 & 0.0423 & -0.0081 & 0.0022 & 0.0049 & 0.0037 & 0.0028 & -0.0065 \\ 0.0115 & 1.105 & -0.0050 & 0.0027 & -0.0018 & -0.0040 & -0.0054 & -0.0065 \\ -0.0035 & -0.0050 & 0.981 & 0.0005 & -0.0025 & 0.0002 & -0.0037 & -0.0048 \\ 0.00078 & 0.0034 & 0.0006 & 1.002 & -0.0032 & -0.0040 & 0.0003 & 0.0018 \\ 0.001126 & -0.0023 & -0.0032 & -0.0032 & 1.055 & 0.001 & -0.004 & 0.0023 \\ 0.00176 & -0.0050 & 0.00036 & -0.0040 & 0.0011 & 0.96 & -0.0057 & 0.0009 \\ 0.0016 & -0.005 & -0.003 & 0.00029 & -0.003 & -0.004 & 0.9543 & 0.0000 \\ -0.0019 & -0.0065 & -0.004 & 0.001 & 0.0018 & 0.0007 & 0.000 & 1.098 \end{pmatrix}$$

- Inverting the matrix is simple, and doable

$$A_{reco \rightarrow gen} =$$

$$\begin{pmatrix} 0.9434 & -0.036 & 0.007 & -0.0020 & -0.0044 & -0.0038 & -0.0030 & 0.0054 \\ -0.009 & 0.90 & 0.0045 & -0.0024 & 0.0016 & 0.003873 & 0.00527 & 0.005 \\ 0.003 & 0.00454 & 1.019 & -0.00058 & 0.0025 & -0.000291 & 0.004 & 0.004 \\ -0.00071 & -0.0030 & -0.0007 & 0.9977 & 0.0030 & 0.004206 & -0.0003 & -0.0017 \\ -0.001 & 0.0020 & 0.0031 & 0.0030 & 0.9483 & -0.0010 & 0.004626 & -0.0019 \\ -0.001 & 0.004 & -0.0003 & 0.0042 & -0.001087 & 1.037 & 0.0063 & -0.0009 \\ -0.0017 & 0.0053 & 0.0042 & -0.0002 & 0.00370 & 0.0050 & 1.048 & 0.0000 \\ 0.0016 & 0.0053 & 0.00452 & -0.001 & -0.001582 & -0.0007213 & 0.000 & 0.9105 \end{pmatrix}$$



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# Sensitivity to unknowns

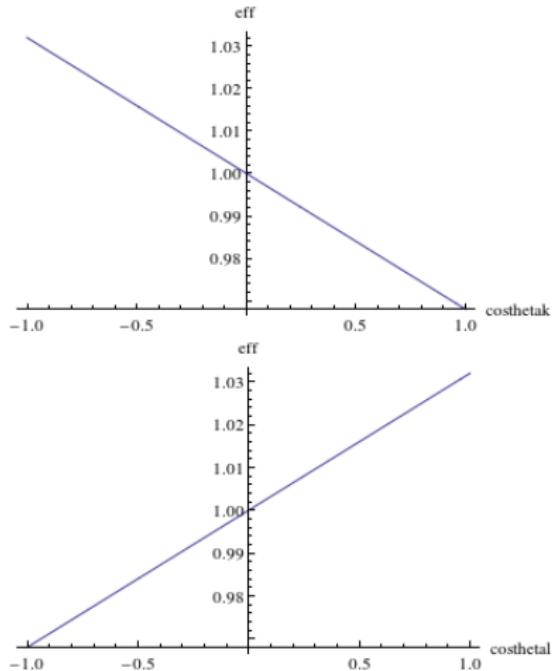
- We are unfolding based on MC.
- There are MC/Data differences, which can have impact on the unfolding.

Let's put small modification:

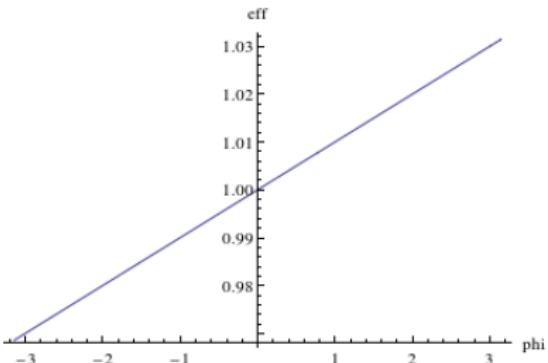
$$w_j \rightarrow \overline{w_j} = \frac{1}{\text{eff}(\cos \theta_{l,j}, \cos \theta_{k,j}, \phi_j)} \times \text{corr}(\cos \theta_{l,j}, \cos \theta_{k,j}, \phi_j) \quad (9)$$

Unfortunately God didn't allowed me sneak peak into his cards so I don't know  $\text{corr}(\cos \theta_l, \cos \theta_k, \phi)$ , but let's try out some functions and see what happens :)

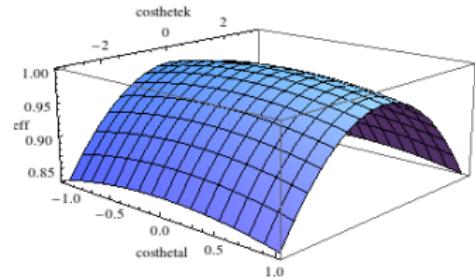
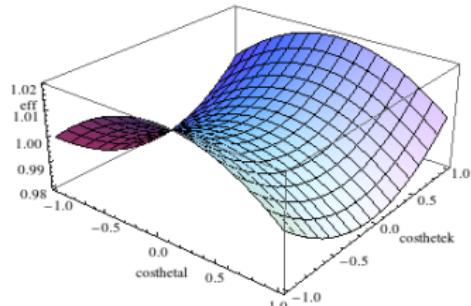
# Corr1 functions



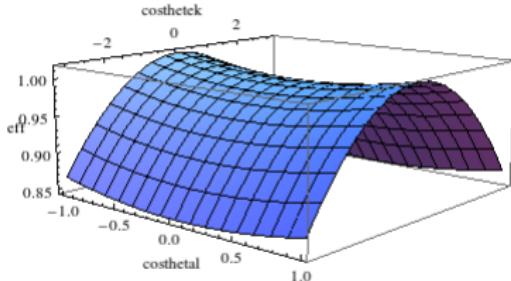
$$\text{corr1}(\cos_l, \cos_k, \phi) = \\ 1 + 0.032 \cos_l - 0.032 \cos_k + 0.01\phi$$



# Corr2 functions



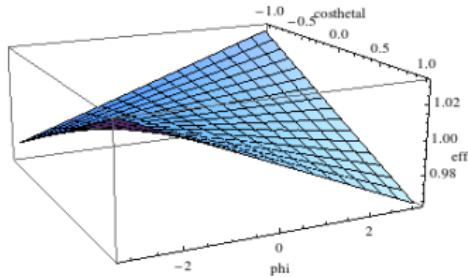
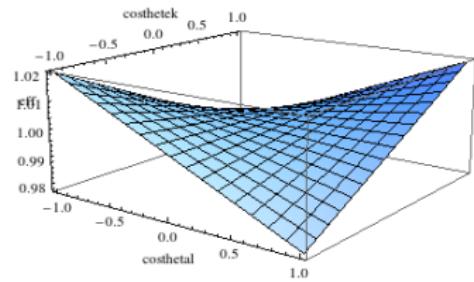
$$\begin{aligned} \text{corr2}(\cos_l, \cos_k, \phi) = \\ -0.02 \cos_l^2 + 0.02 \cos_k^2 - 0.015 \phi^2 + 1 \end{aligned}$$



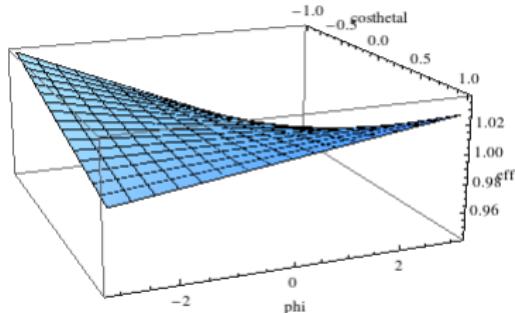
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# Corr3 functions



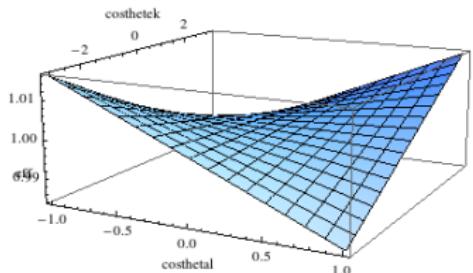
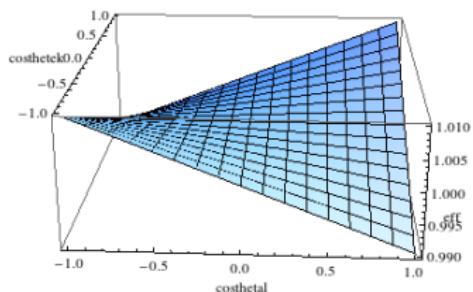
$$\begin{aligned}\text{corr3}(\cos_l, \cos_k, \phi) = \\ 0.02 \cos_l \cos_k + 0.01 \cos_k \phi - \\ 0.01 \phi \cos_l + 1\end{aligned}$$



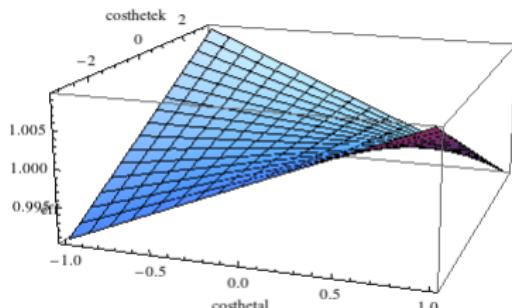
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# Corr4 functions



$$\text{corr3}(\cos_l, \cos_k, \phi) = \\ 0.01 \cos_k \cos_l \phi + 1$$



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# Corr1- MM

Mean of the pull

$q^2$	$S_3$	$S_4$	$S_5$	$S_{6s}$	$S_{6c}$	$S_7$	$S_8$
0	0.0085 ± 0.026(0.3)	0.13 ± 0.027(4.6)	-0.025 ± 0.027(-0.92)	0.46 ± 0.027(17)	-0.13 ± 0.028(-4.7)	0.029 ± 0.028(1)	-0.66 ± 0.027(-25)
1	0.0094 ± 0.028(0.33)	0.078 ± 0.028(2.8)	-0.02 ± 0.028(-0.73)	0.24 ± 0.028(8.5)	-0.075 ± 0.028(-2.7)	-0.016 ± 0.026(-0.63)	-0.39 ± 0.028(-14)
2	-0.02 ± 0.027(-0.72)	0.027 ± 0.026(1)	-0.024 ± 0.027(-0.91)	0.18 ± 0.027(6.8)	-0.024 ± 0.027(-0.89)	-0.067 ± 0.027(-2.5)	-0.39 ± 0.028(-14)
3	0.013 ± 0.028(0.46)	-0.0089 ± 0.027(-0.32)	0.055 ± 0.026(2.1)	0.12 ± 0.027(4.7)	0.11 ± 0.027(3.9)	-0.018 ± 0.028(-0.63)	-0.43 ± 0.027(-16)
4	-0.0054 ± 0.029(-0.18)	-0.066 ± 0.027(-2.4)	0.037 ± 0.028(1.3)	0.22 ± 0.027(8.1)	0.099 ± 0.027(3.7)	-0.1 ± 0.026(-3.8)	-0.41 ± 0.026(-15)
5	0.06 ± 0.027(2.2)	-0.069 ± 0.026(-2.6)	-0.013 ± 0.028(-0.49)	0.21 ± 0.027(7.8)	0.093 ± 0.027(3.5)	-0.083 ± 0.028(-3)	-0.41 ± 0.028(-15)
6	0.0064 ± 0.026(0.25)	-0.051 ± 0.027(-1.9)	-0.029 ± 0.028(-1)	0.26 ± 0.028(9.2)	0.14 ± 0.027(5.1)	-0.081 ± 0.027(-3)	-0.45 ± 0.028(-16)
8	0.023 ± 0.027(0.85)	-0.031 ± 0.028(-1.1)	0.0042 ± 0.028(0.15)	0.21 ± 0.026(7.8)	0.12 ± 0.028(4.2)	-0.13 ± 0.027(-4.8)	-0.48 ± 0.026(-18)
9	-0.017 ± 0.027(-0.63)	-0.015 ± 0.026(-0.56)	-0.0052 ± 0.026(-0.2)	0.27 ± 0.027(10)	0.046 ± 0.026(1.7)	-0.12 ± 0.026(-4.4)	-0.5 ± 0.026(-19)
10	-0.054 ± 0.027(-2)	-0.056 ± 0.026(-2.2)	0.036 ± 0.026(1.4)	0.16 ± 0.028(5.7)	0.077 ± 0.028(2.8)	-0.034 ± 0.027(-1.3)	-0.39 ± 0.028(-14)
11	0.023 ± 0.027(0.88)	0.021 ± 0.027(0.8)	-0.011 ± 0.027(-0.41)	0.14 ± 0.027(5)	0.042 ± 0.027(1.6)	-0.098 ± 0.028(-3.5)	-0.3 ± 0.027(-11)



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# Corr2- MM

Mean of the pull							
$q^2$	$S_3$	$S_4$	$S_5$	$S_{6s}$	$S_{6c}$	$S_7$	$S_8$
0	-0.21 ± 0.026(-8.1)	0.061 ± 0.026(2.3)	-0.016 ± 0.026(-0.63)	0.048 ± 0.026(1.8)	-0.0062 ± 0.027(-0.23)	-0.012 ± 0.028(-0.44)	0.0091 ± 0.026(0.36)
1	-0.12 ± 0.028(-4.5)	0.032 ± 0.027(1.2)	-0.0071 ± 0.026(-0.27)	0.02 ± 0.027(0.75)	-0.086 ± 0.027(-3.2)	-0.03 ± 0.025(-1.2)	0.021 ± 0.027(0.79)
2	-0.15 ± 0.027(-5.8)	-0.013 ± 0.026(-0.49)	0.011 ± 0.026(0.44)	-0.039 ± 0.026(-1.5)	-0.032 ± 0.027(-1.2)	-0.066 ± 0.027(-2.5)	0.018 ± 0.028(0.64)
3	-0.15 ± 0.027(-5.6)	0.025 ± 0.026(0.96)	0.016 ± 0.027(0.58)	-0.062 ± 0.027(-2.3)	0.037 ± 0.026(1.4)	0.026 ± 0.027(0.96)	-0.016 ± 0.027(-0.1)
4	-0.12 ± 0.028(-4.5)	-0.024 ± 0.026(-0.92)	0.045 ± 0.027(1.6)	0.0075 ± 0.026(0.29)	0.015 ± 0.027(0.53)	-0.036 ± 0.026(-1.4)	0.037 ± 0.026(1.4)
5	-0.095 ± 0.027(-3.6)	-0.032 ± 0.026(-1.2)	0.014 ± 0.026(0.52)	-0.013 ± 0.026(-0.46)	-0.0093 ± 0.027(-0.35)	-0.013 ± 0.026(-0.51)	0.042 ± 0.027(1.6)
6	-0.17 ± 0.025(-6.5)	0.008 ± 0.027(0.3)	0.012 ± 0.027(0.45)	0.029 ± 0.027(1.1)	0.0072 ± 0.027(0.27)	-0.0012 ± 0.026(-0.046)	0.011 ± 0.027(0.42)
8	-0.13 ± 0.026(-5.1)	-0.0077 ± 0.027(-0.28)	0.05 ± 0.027(1.9)	-0.03 ± 0.026(-1.2)	-0.012 ± 0.028(-0.44)	-0.046 ± 0.026(-1.7)	0.031 ± 0.026(1.2)
9	-0.15 ± 0.026(-5.7)	-0.0083 ± 0.026(-0.32)	0.03 ± 0.026(1.2)	0.044 ± 0.027(1.6)	-0.07 ± 0.026(-2.7)	-0.022 ± 0.026(-0.84)	-0.045 ± 0.026(-1.1)
10	-0.15 ± 0.029(-5.8)	-0.032 ± 0.029(-1.3)	0.059 ± 0.026(2.2)	-0.072 ± 0.028(-2.6)	-0.029 ± 0.027(-1.1)	0.064 ± 0.027(2.4)	0.014 ± 0.027(0.51)
11	-0.067 ± 0.026(-2.6)	0.017 ± 0.026(0.65)	-0.015 ± 0.026(-0.56)	-0.051 ± 0.026(-1.9)	-0.0086 ± 0.026(-0.33)	-0.018 ± 0.028(-0.67)	0.017 ± 0.027(0.62)

# Corr3- MM

Mean of the pull							
$q^2$	$S_3$	$S_4$	$S_5$	$S_{6s}$	$S_{6c}$	$S_7$	$S_8$
0	$-0.021 \pm 0.026(-0.81)$	$0.041 \pm 0.026(1.5)$	$0.009 \pm 0.027(0.34)$	$0.043 \pm 0.026(1.6)$	$0.13 \pm 0.028(4.8)$	$-0.0072 \pm 0.028(-0.26)$	$0.044 \pm 0.026(1.7)$
1	$-0.014 \pm 0.028(-0.51)$	$0.03 \pm 0.027(1.1)$	$0.022 \pm 0.027(0.82)$	$0.015 \pm 0.028(0.53)$	$0.078 \pm 0.028(2.8)$	$-0.037 \pm 0.029(-1.4)$	$0.057 \pm 0.027(2.1)$
2	$-0.037 \pm 0.027(-1.4)$	$-0.0013 \pm 0.027(-0.048)$	$-0.015 \pm 0.027(-0.54)$	$-0.052 \pm 0.026(-2)$	$0.1 \pm 0.027(3.8)$	$-0.051 \pm 0.026(-1.9)$	$0.022 \pm 0.028(0.78)$
3	$-0.015 \pm 0.027(-0.55)$	$0.036 \pm 0.028(1.3)$	$-0.039 \pm 0.027(-1.4)$	$-0.072 \pm 0.027(-2.7)$	$0.17 \pm 0.027(6.2)$	$-0.0044 \pm 0.028(-0.15)$	$-0.024 \pm 0.027(-0.9)$
4	$-0.00047 \pm 0.029(-0.017)$	$-0.012 \pm 0.027(-0.43)$	$0.0099 \pm 0.028(0.35)$	$-0.002 \pm 0.026(-0.076)$	$0.17 \pm 0.028(6.2)$	$-0.062 \pm 0.027(-2.3)$	$0.0086 \pm 0.027(0.32)$
5	$0.046 \pm 0.027(1.7)$	$-0.02 \pm 0.026(-0.76)$	$-0.04 \pm 0.027(-1.5)$	$-0.012 \pm 0.027(-0.44)$	$0.13 \pm 0.027(4.8)$	$-0.04 \pm 0.027(-1.5)$	$-0.0056 \pm 0.027(-0.7)$
6	$-0.013 \pm 0.026(-0.52)$	$0.041 \pm 0.027(1.5)$	$-0.033 \pm 0.028(-1.2)$	$-0.0019 \pm 0.027(-0.068)$	$0.15 \pm 0.027(5.4)$	$-0.034 \pm 0.027(-1.3)$	$-0.021 \pm 0.028(-0.7)$
8	$0.039 \pm 0.026(1.5)$	$0.01 \pm 0.028(0.36)$	$-0.027 \pm 0.028(-0.96)$	$-0.024 \pm 0.026(-0.9)$	$0.12 \pm 0.027(4.3)$	$-0.092 \pm 0.026(-3.5)$	$-0.036 \pm 0.027(-1.3)$
9	$-0.01 \pm 0.027(-0.38)$	$0.0024 \pm 0.027(0.09)$	$-0.018 \pm 0.026(-0.68)$	$0.022 \pm 0.028(0.79)$	$0.068 \pm 0.027(2.6)$	$-0.069 \pm 0.026(-2.6)$	$-0.078 \pm 0.026(-3)$
10	$-0.017 \pm 0.027(-0.62)$	$-0.015 \pm 0.026(-0.57)$	$0.012 \pm 0.027(0.46)$	$-0.074 \pm 0.028(-2.6)$	$0.1 \pm 0.027(3.8)$	$-0.003 \pm 0.027(-0.11)$	$-0.043 \pm 0.029(-1.5)$
11	$0.032 \pm 0.026(1.2)$	$0.024 \pm 0.026(0.91)$	$-0.04 \pm 0.026(-1.5)$	$-0.066 \pm 0.027(-2.5)$	$0.098 \pm 0.027(3.7)$	$-0.043 \pm 0.028(-1.6)$	$-0.0018 \pm 0.028(-0.7)$

# Corr4- MM

Mean of the pull							
$q^2$	$S_3$	$S_4$	$S_5$	$S_{6s}$	$S_{6c}$	$S_7$	$S_8$
0	-0.019 ± 0.026(-0.71)	0.048 ± 0.027(1.8)	0.018 ± 0.027(0.67)	0.059 ± 0.027(2.2)	-0.015 ± 0.028(-0.55)	0.061 ± 0.027(2.2)	0.012 ± 0.027(0.44)
1	-0.014 ± 0.028(-0.51)	0.043 ± 0.027(1.6)	0.013 ± 0.027(0.49)	0.024 ± 0.028(0.86)	-0.038 ± 0.028(-1.4)	0.024 ± 0.026(0.94)	0.037 ± 0.027(1.3)
2	-0.03 ± 0.027(-1.1)	-0.0021 ± 0.027(-0.076)	-0.01 ± 0.027(-0.39)	-0.017 ± 0.027(-0.61)	-0.016 ± 0.027(-0.58)	0.013 ± 0.027(0.49)	0.027 ± 0.028(0.98)
3	-0.007 ± 0.027(-0.26)	0.03 ± 0.028(1.1)	-0.036 ± 0.027(-1.3)	-0.074 ± 0.027(-2.8)	0.041 ± 0.027(1.5)	0.08 ± 0.028(2.9)	-0.0083 ± 0.027(-0.31)
4	0.00089 ± 0.029(0.031)	-0.021 ± 0.027(-0.77)	0.0032 ± 0.028(0.11)	0.0031 ± 0.026(0.12)	0.012 ± 0.027(0.44)	0.019 ± 0.026(0.71)	0.034 ± 0.027(1.3)
5	0.044 ± 0.028(1.6)	-0.022 ± 0.026(-0.82)	-0.041 ± 0.027(-1.5)	-0.014 ± 0.027(-0.53)	-0.029 ± 0.027(-1.1)	0.041 ± 0.027(1.5)	0.042 ± 0.028(1.5)
6	-0.011 ± 0.026(-0.42)	0.041 ± 0.027(1.5)	-0.045 ± 0.028(-1.6)	0.011 ± 0.027(0.41)	-0.0089 ± 0.027(-0.33)	0.067 ± 0.027(2.5)	0.036 ± 0.027(1.3)
8	0.05 ± 0.026(1.9)	0.0021 ± 0.028(0.074)	-0.025 ± 0.028(-0.91)	-0.023 ± 0.026(-0.87)	-0.024 ± 0.028(-0.85)	0.022 ± 0.026(0.82)	0.026 ± 0.026(0.98)
9	-0.0064 ± 0.027(-0.23)	0.012 ± 0.027(0.44)	-0.0075 ± 0.026(-0.28)	0.029 ± 0.027(1.1)	-0.087 ± 0.027(-3.2)	0.036 ± 0.027(1.3)	-0.02 ± 0.026(-0.76)
10	-0.019 ± 0.027(-0.71)	-0.0051 ± 0.025(-0.2)	0.0081 ± 0.026(0.31)	-0.077 ± 0.028(-2.7)	-0.03 ± 0.027(-1.1)	0.11 ± 0.027(4.1)	0.013 ± 0.028(0.46)
11	0.027 ± 0.026(1)	0.032 ± 0.027(1.2)	-0.038 ± 0.027(-1.4)	-0.048 ± 0.026(-1.8)	-0.021 ± 0.027(-0.77)	0.019 ± 0.028(0.69)	0.035 ± 0.027(1.3)

# Reverse Engineering- Corr1

- Let's try to understand if we can understand why this happens:
- Let's calculate what should I expect with the unfolding
- This is up to normalization!
  - $M_5 = 0.4S_5 \rightarrow M_5 = 0.00512S_3 + 0.4S_5 - 0.002S_7$
  - $M_8 = 0.32S_8 \rightarrow M_8 = 0.0016S_4 + 0.00512S_7 + 0.32S_8$
  - $M_7 = 0.4S_7 \rightarrow M_7 = 0.002S_5 + 0.4S_7 + 0.00512S_8$
  - $M_3 = 0.32S_3 \rightarrow M_3 = 0.32S_3 - 0.0008S_9$
- The way you can look at this is that i just shown you how our unfolding matrix works like.



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# Reverse Engineering- Corr2

- Let's try to understand if we can understand why this happens:
- Let's calculate what should I expect with the unfolding
- This is up to normalization!
  - $M_5 = 0.4S_5 \rightarrow M_5 = 0.4S_5$
  - $M_8 = 0.32S_8 \rightarrow M_8 = 0.32S_5$
  - $M_7 = 0.4S_7 \rightarrow M_7 = 0.4S_7$
  - $M_3 = 0.32S_3 \rightarrow M_3 = -0.0036 + 0.0012FI + 0.32S_3$
- The way you can look at this is that i just shown you how our unfolding matrix works like.



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# Summary

- Developed a systematic way how to get Unfolding matrix
- Moments are resistant against variety of unfolding discrepancies.
- This might lead to reduced systematics in the future.